

Structural and Practical Identifiability Analysis of partially observed dynamical systems

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Outline

- Introducing structural and practical identifiability
- **1. Profile Likelihood Approach**
Detecting non-identifiabilities
- JAK-STAT Signaling Pathway
- **2. Mean *Optimal Transformation* Approach**
Finding groups of functionally related parameters

Introduction

ODE models

species: $\dot{\vec{x}}(t) = f(\vec{x}(t), \vec{u}(t), \vec{p}, t)$

observables: $\vec{y}(t) = g(\vec{x}(t), \vec{s}) + \vec{\epsilon}(t)$

$$\theta = \{\vec{x}_0, \vec{p}, \vec{s}\} \\ \in \mathbf{R}^+ \setminus \{0\}$$

Signaling pathways

	species	observables	parameters	data-points
JAK-STAT	4	2	7	32
EPO receptor	6	3	10	32
JAK2-STAT5	13	6	20	213
TNF α IL-1 IL-6	20	6	24	159
MAPK	24	12	68	168

Introduction

ODE models

species: $\dot{\vec{x}}(t) = f(\vec{x}(t), \vec{u}(t), \vec{p}, t)$

observables: $\vec{y}(t) = g(\vec{x}(t), \vec{s}) + \vec{\epsilon}(t)$

$$\theta = \{\vec{x}_0, \vec{p}, \vec{s}\}$$

$$\in \mathbf{R}^+ \setminus \{0\}$$

Objective function: Log-Likelihood

$$\chi^2(\theta) = \sum_{k=1}^m \sum_{l=1}^{d_i} \left(\frac{y_{kl}^D - y_k(\theta, t_{kl})}{\sigma_{kl}^D} \right)^2 \quad \vec{\epsilon}(t) \sim N(0, \sigma^2)$$

$$\hat{\theta} = \arg \min [\chi^2(\theta)]$$



POTTERS WHEEL
Multi-Experiment Fitting



www.PottersWheel.de

Introduction

Structural non-identifiability

$$\dot{\vec{x}}(t) = f(\vec{x}(t), \vec{u}(t), \vec{p}, t)$$

$$\vec{y}(t) = g(\vec{x}(t), \vec{s}) + \vec{\epsilon}(t)$$

Simple example: $A \xrightarrow{k} B$

$$\dot{A}(t) = -k \cdot A(t)$$

$$\theta = \{A_0, B_0, k\}$$

$$\dot{B}(t) = +k \cdot A(t)$$

$$y(t) = A(t) + B(t)$$

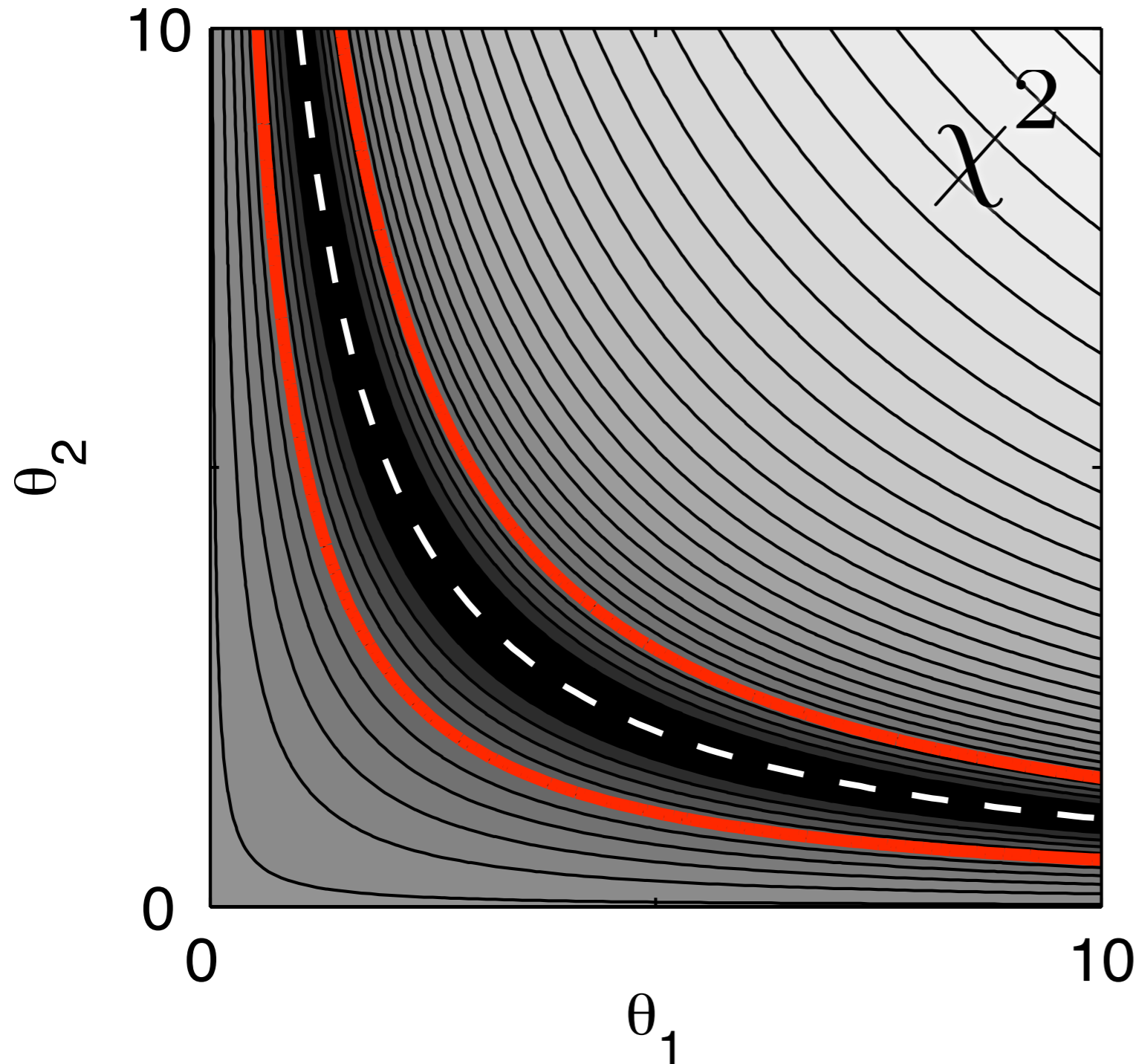
$$= A_0 \cdot e^{-k \cdot t} + [B_0 + A_0 \cdot (1 - e^{k \cdot t})]$$

$$= A_0 + B_0$$

Cobelli, C. and DiStefano, J. (1980). *Parameter and structural identifiability concepts and ambiguities: a critical review and analysis*. American Journal of Physiology- Regulatory, Integrative and Comparative Physiology, 239(1), 7–24.

Introduction

Structural non-identifiability (data-based view)



Functional relation:

$$\theta_1 \cdot \theta_2 = 10$$

Introduction

Practical non-identifiability & Confidence intervals

Asymptotic confidence intervals

$$\sigma_i^{\pm} = \hat{\theta}_i \pm \sqrt{\chi^2(1 - \alpha, df) \cdot \mathbf{C}_{ii}}$$

$$\text{with } \mathbf{C} = \mathbf{H}^{-1} \quad \text{and} \quad \mathbf{H} = \nabla^T \nabla \chi^2 |_{\hat{\theta}_i}$$

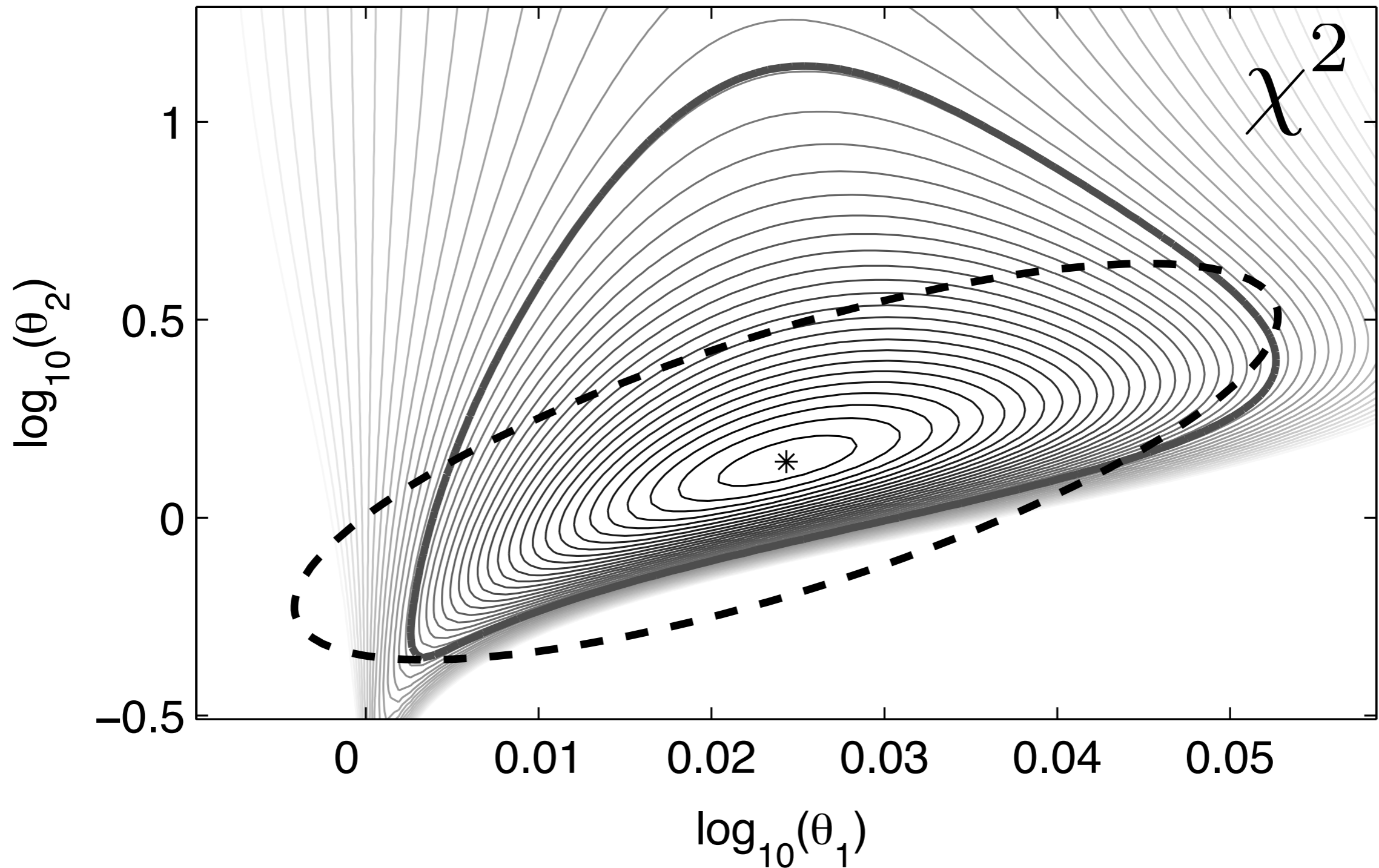
Likelihood-based confidence intervals

$$\{\theta \mid \chi^2(\theta) - \chi^2(\hat{\theta}) < \Delta_{\alpha}\}$$

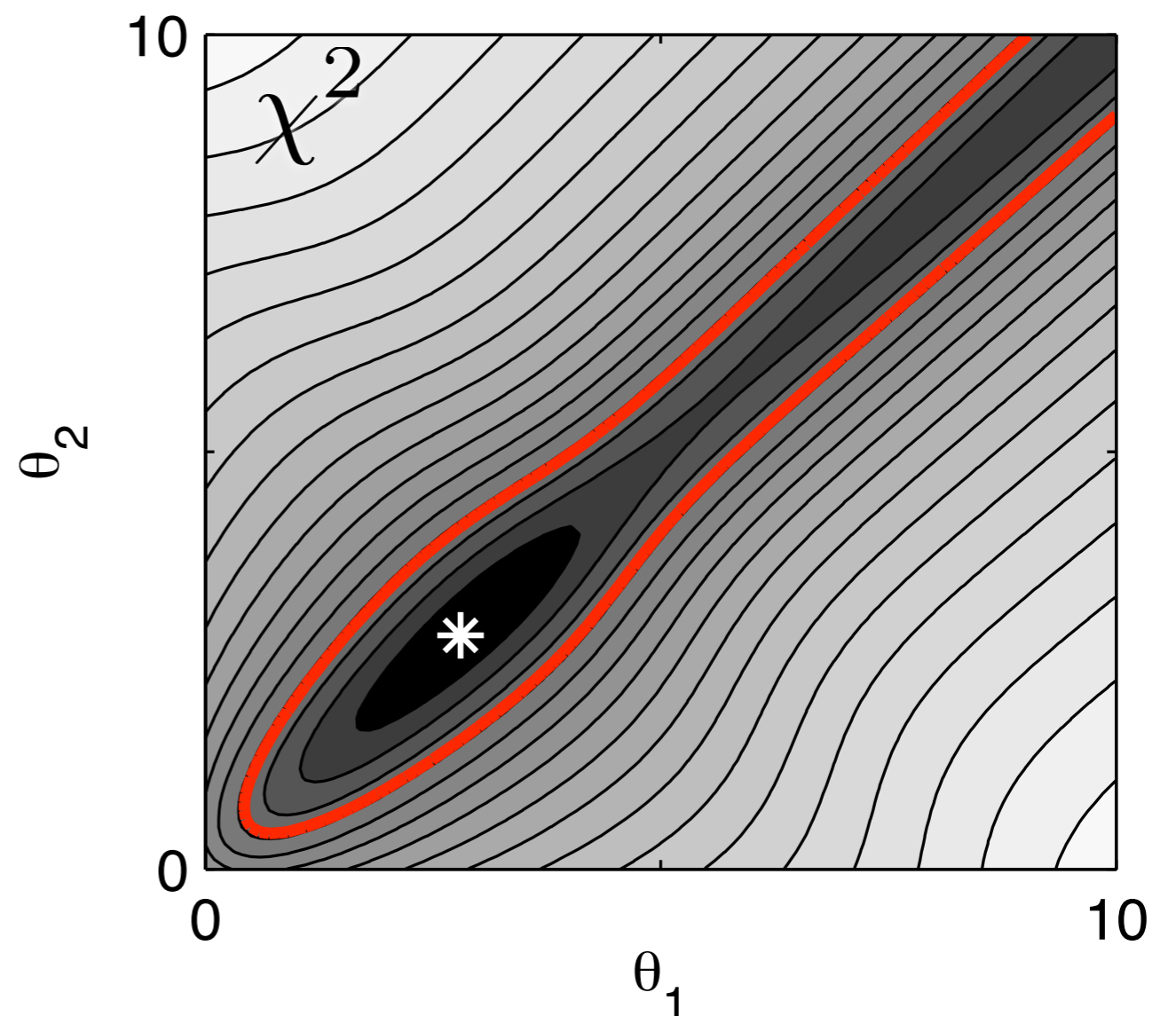
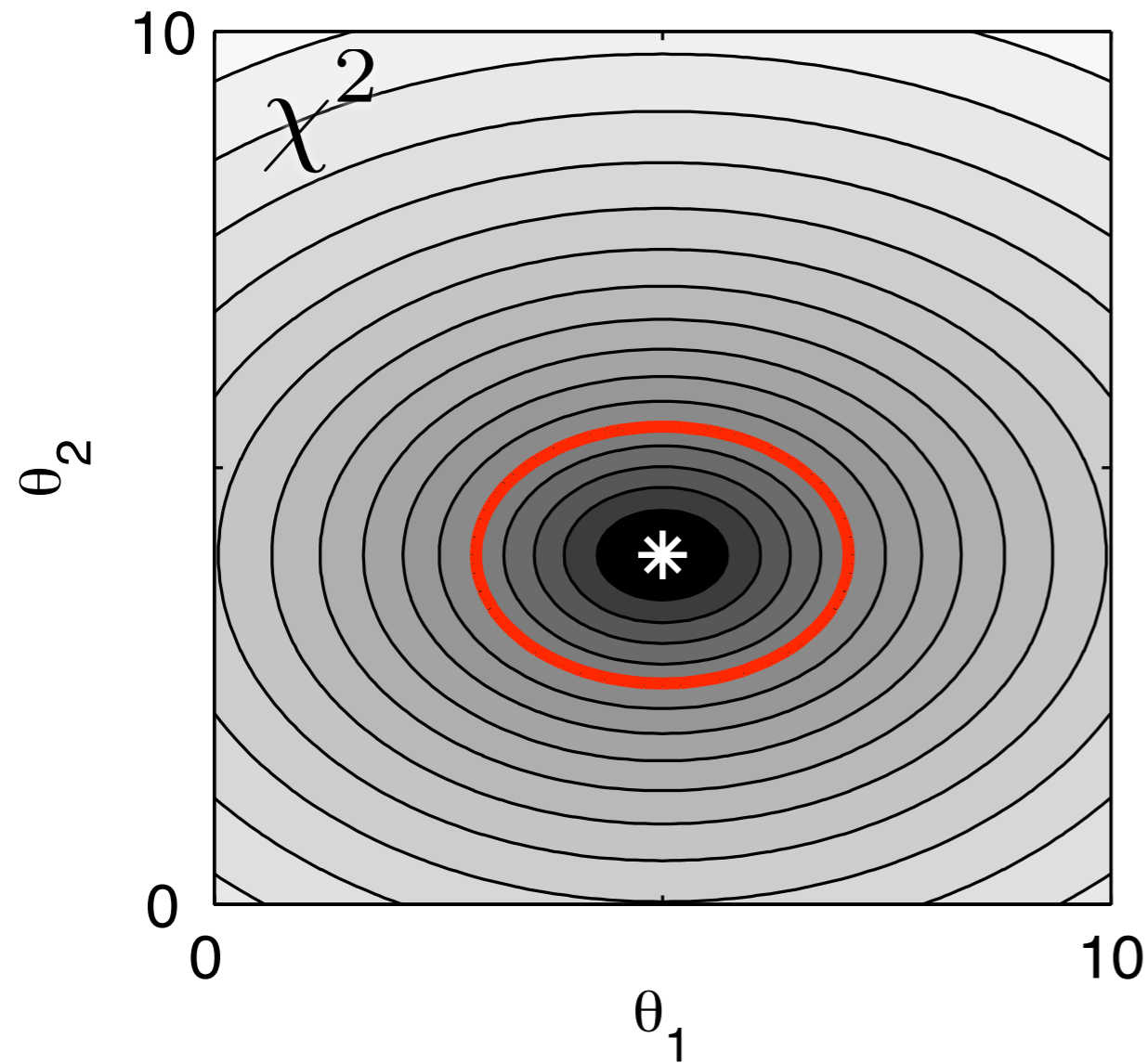
$$\text{with } \Delta_{\alpha} = \chi^2(1 - \alpha, df)$$

Introduction

Asymptotic vs. likelihood-based confidence intervals



Introduction



Practical non-identifiability: Likelihood-based confidence region infinitely extended.

I. Profile Likelihood Approach

Structural non-identifiability → Likelihood perfectly flat

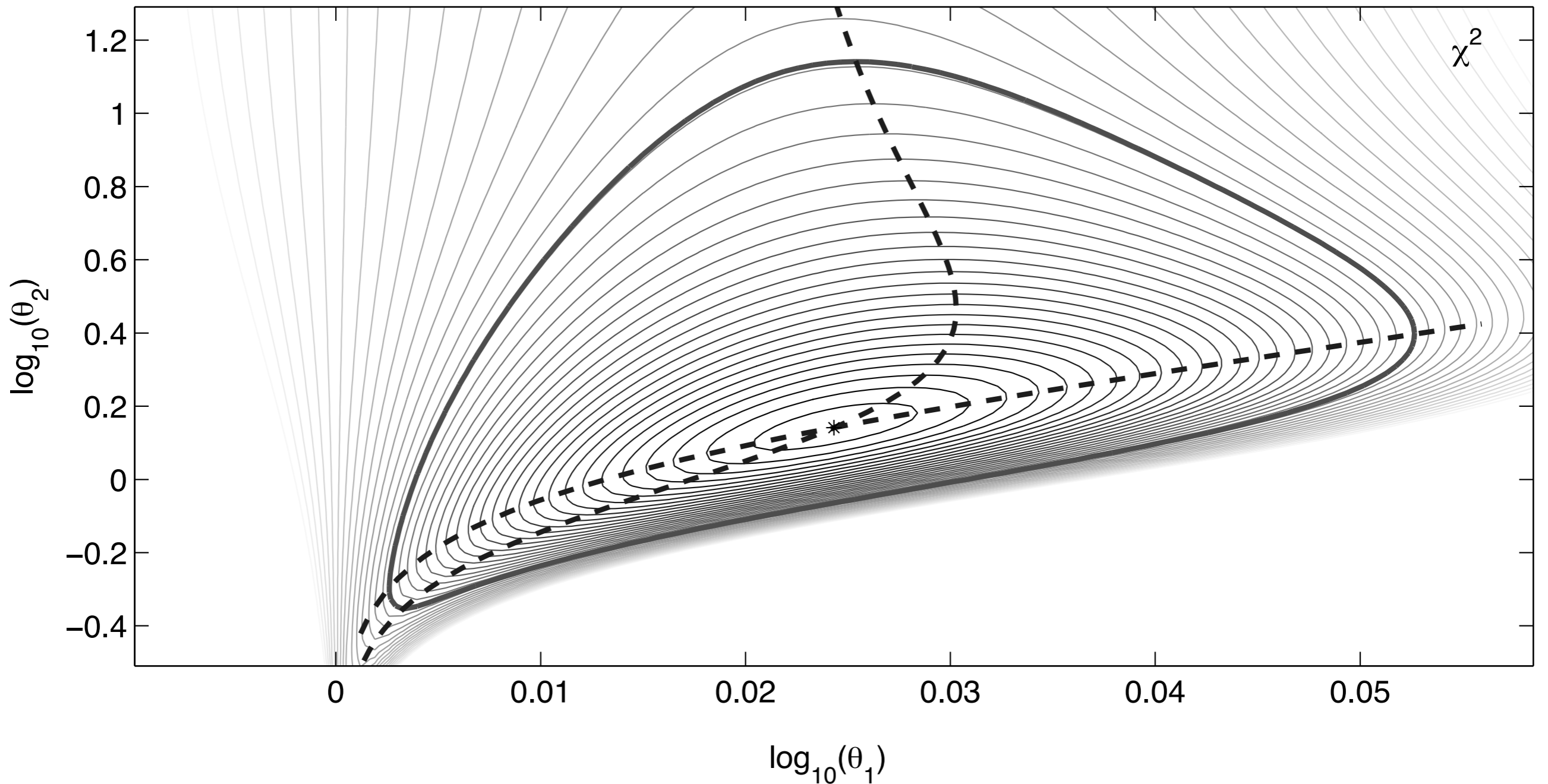
Practical non-identifiability → Likelihood flattens out

Idea: Sample the profile likelihood

$$\chi_{PL}^2(\theta_i) = \min_{\forall \theta_{j \neq i}} [\chi^2(\theta)]$$

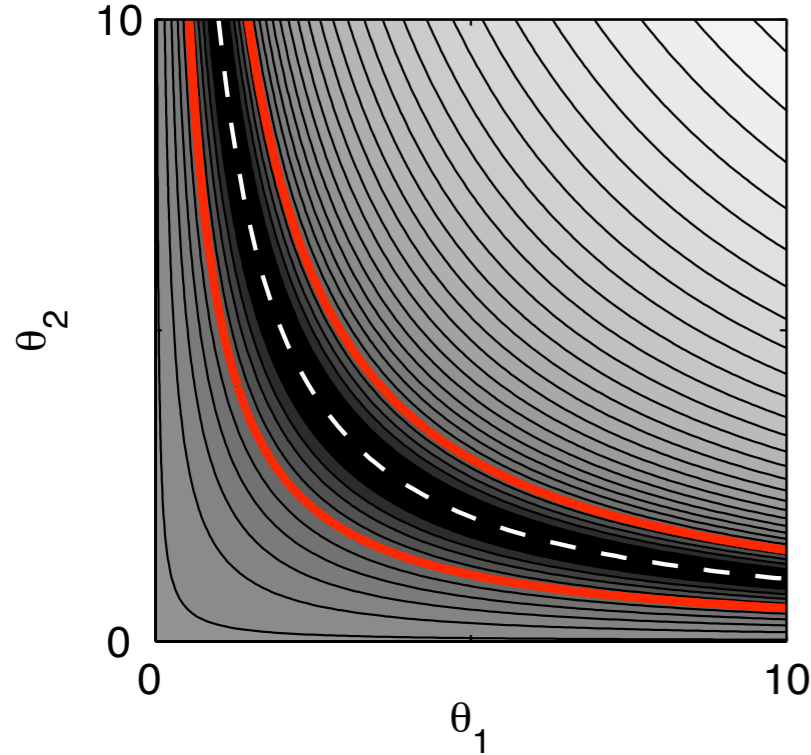
I. Profile Likelihood Approach

The profile likelihood $\chi_{PL}^2(\theta_i) = \min_{\forall \theta_{j \neq i}} [\chi^2(\theta)]$

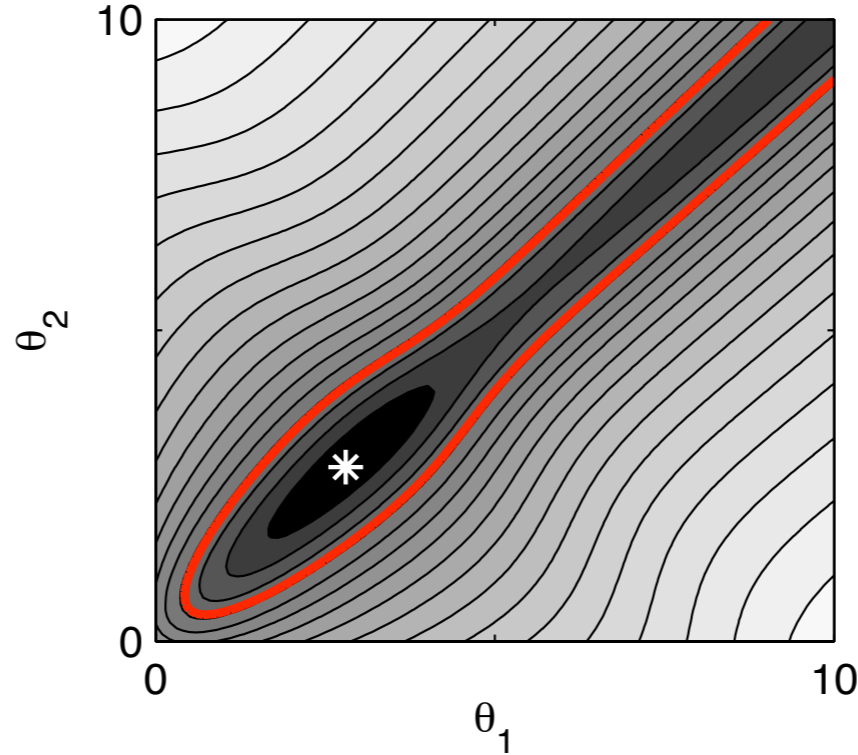


I. Profile Likelihood Approach

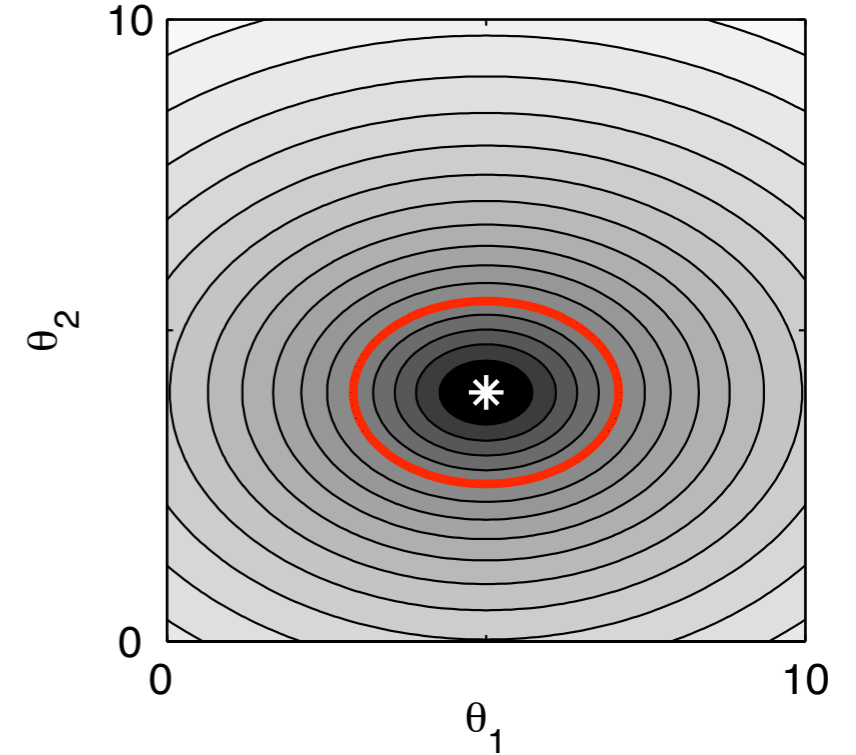
structurally
non-identifiable



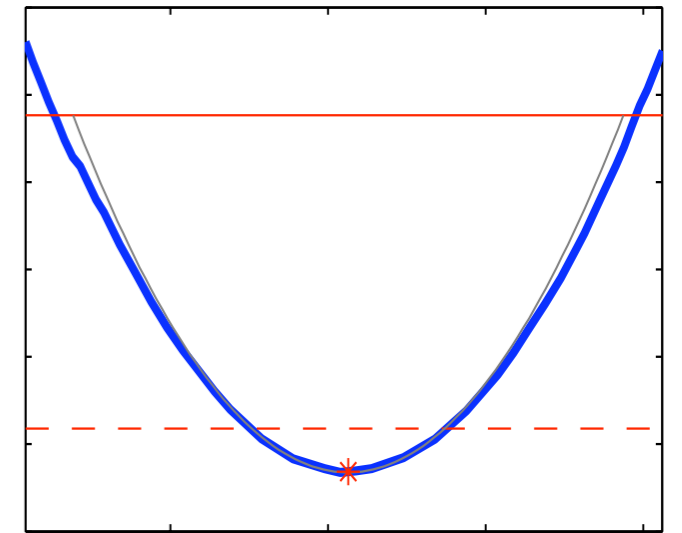
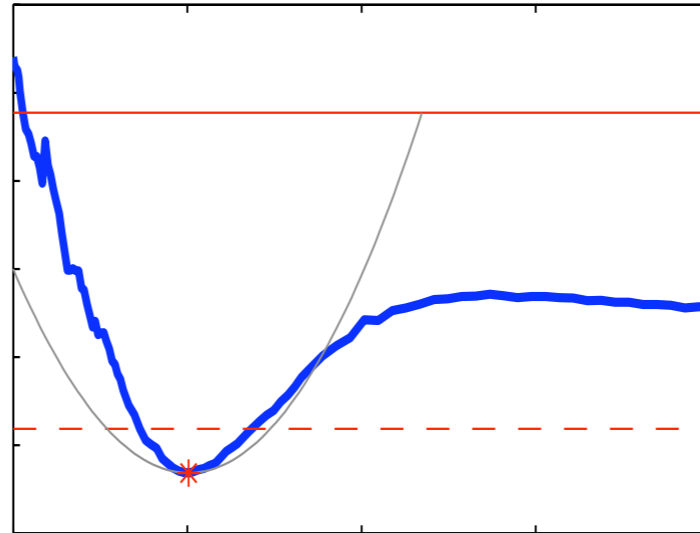
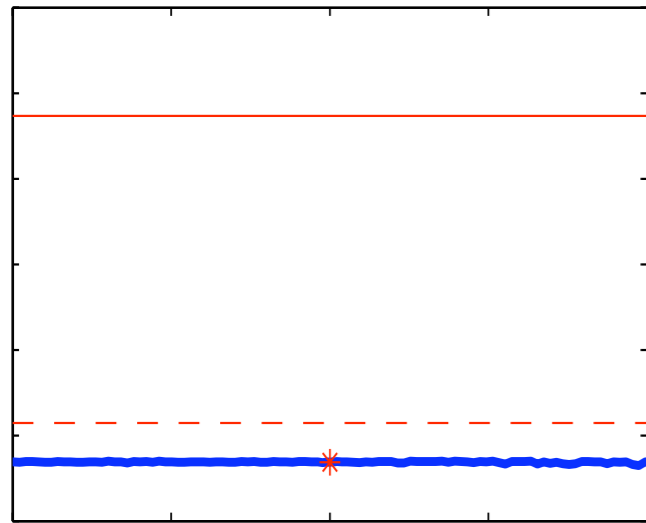
practically
non-identifiable



identifiable



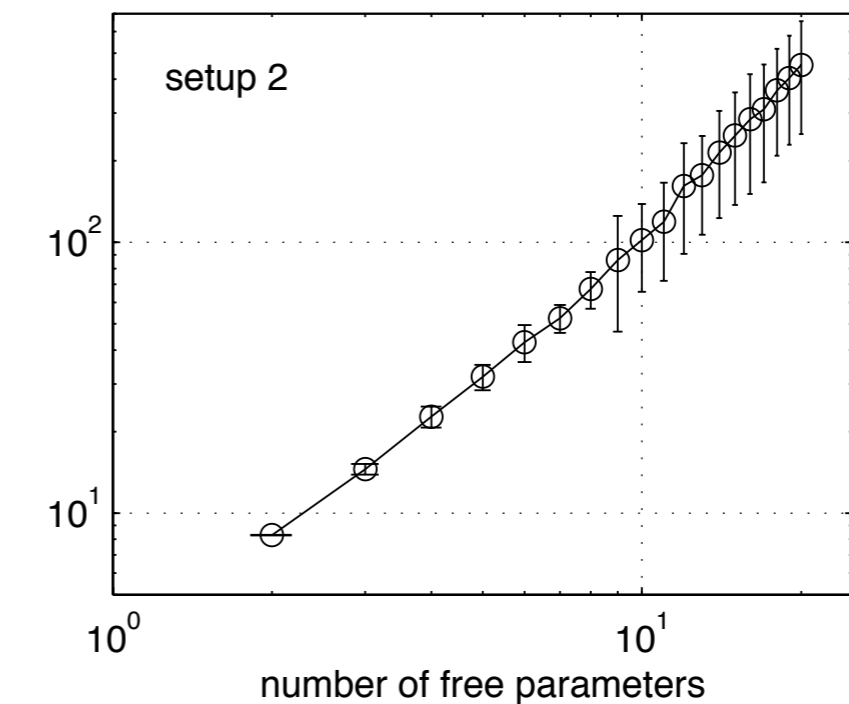
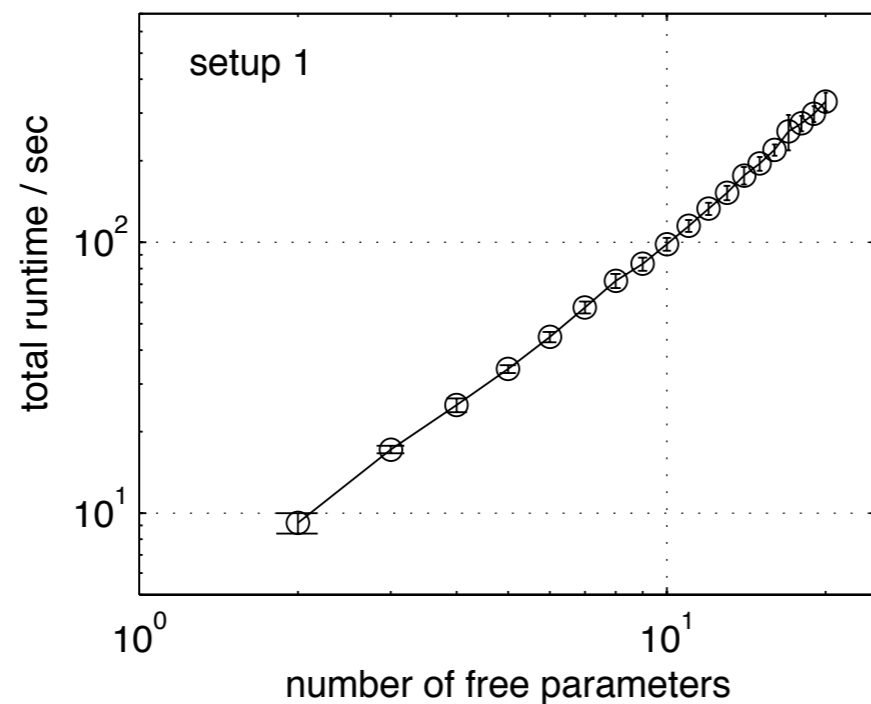
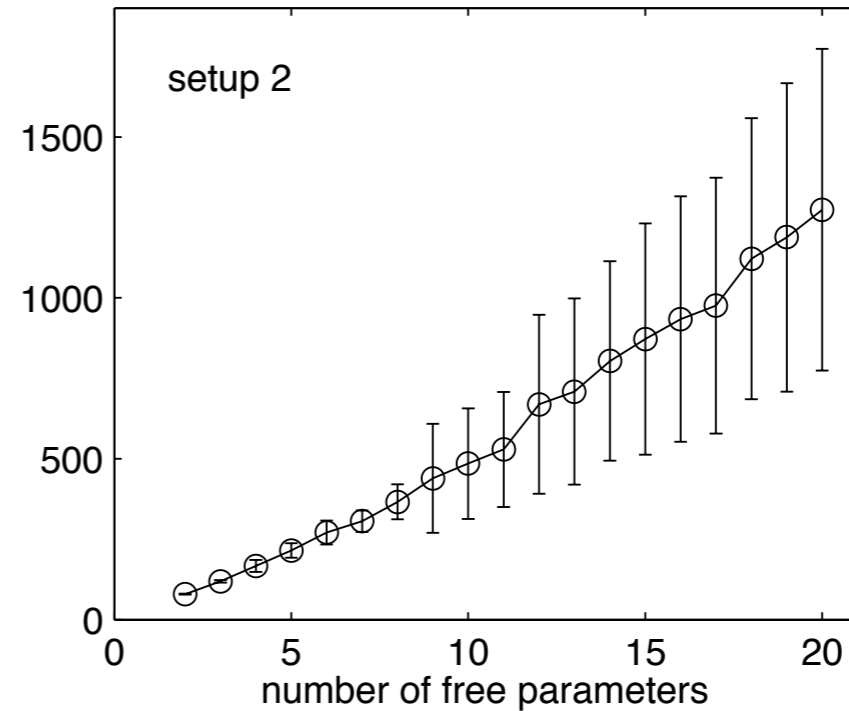
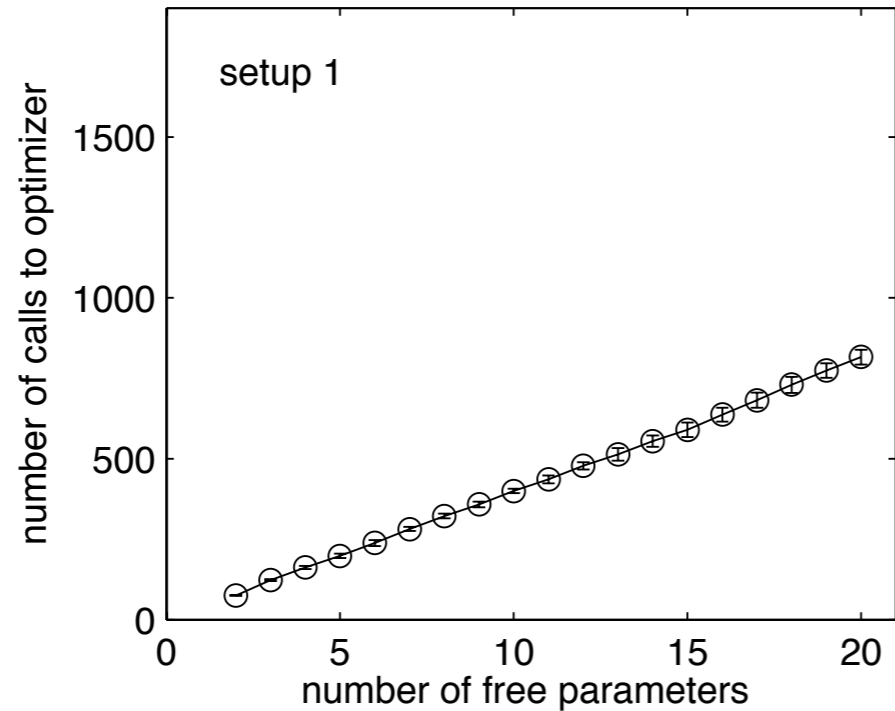
$\chi^2_{PL}(\theta_1)$



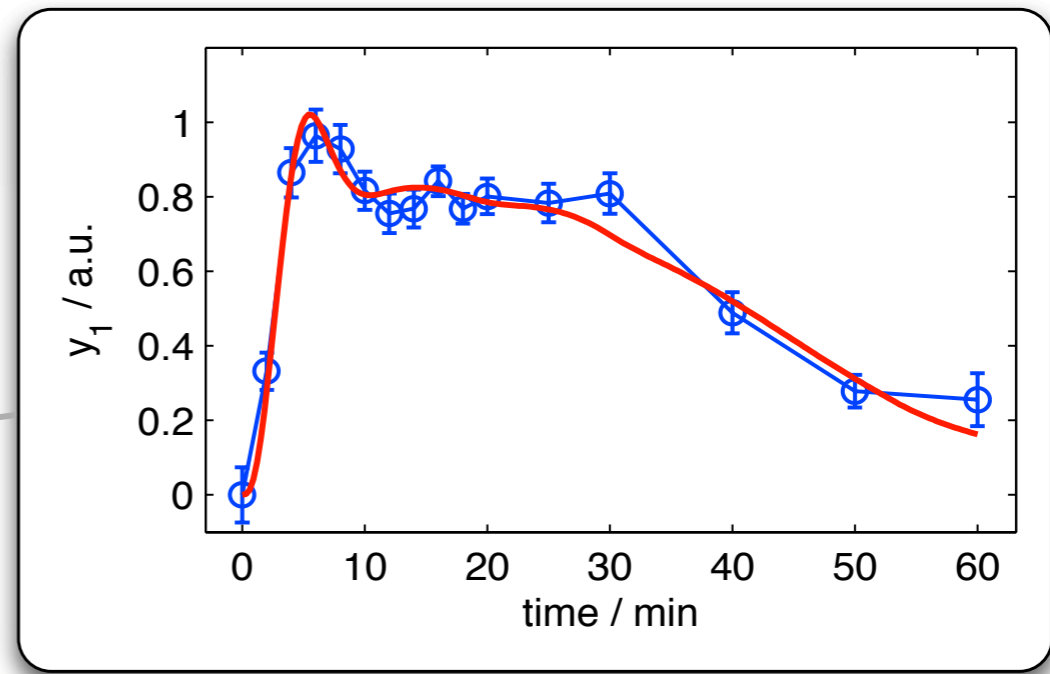
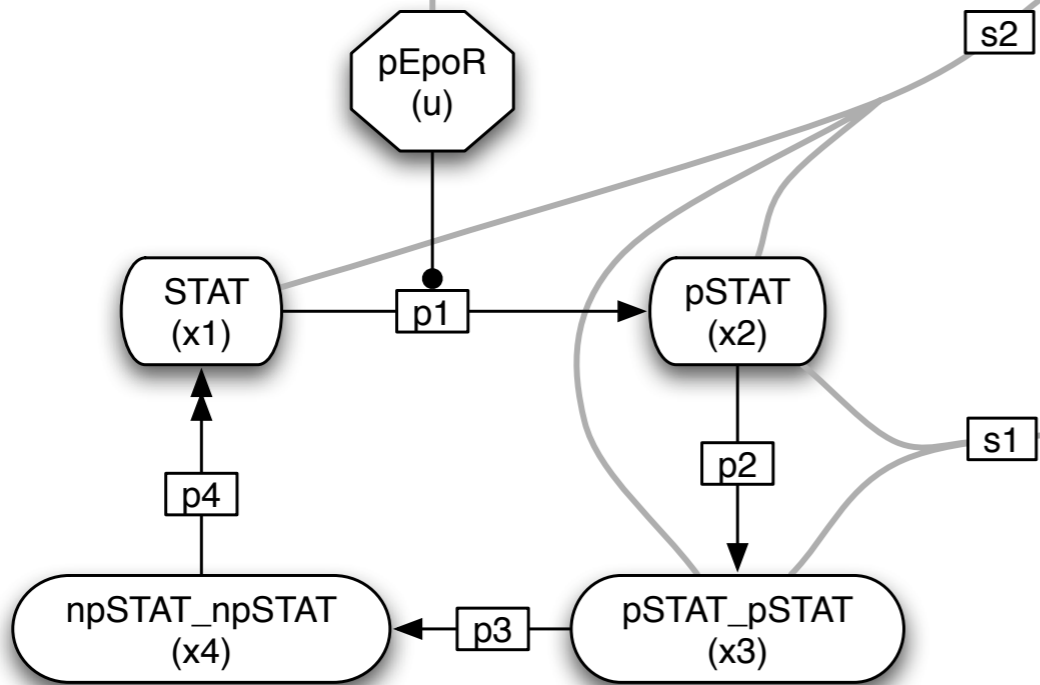
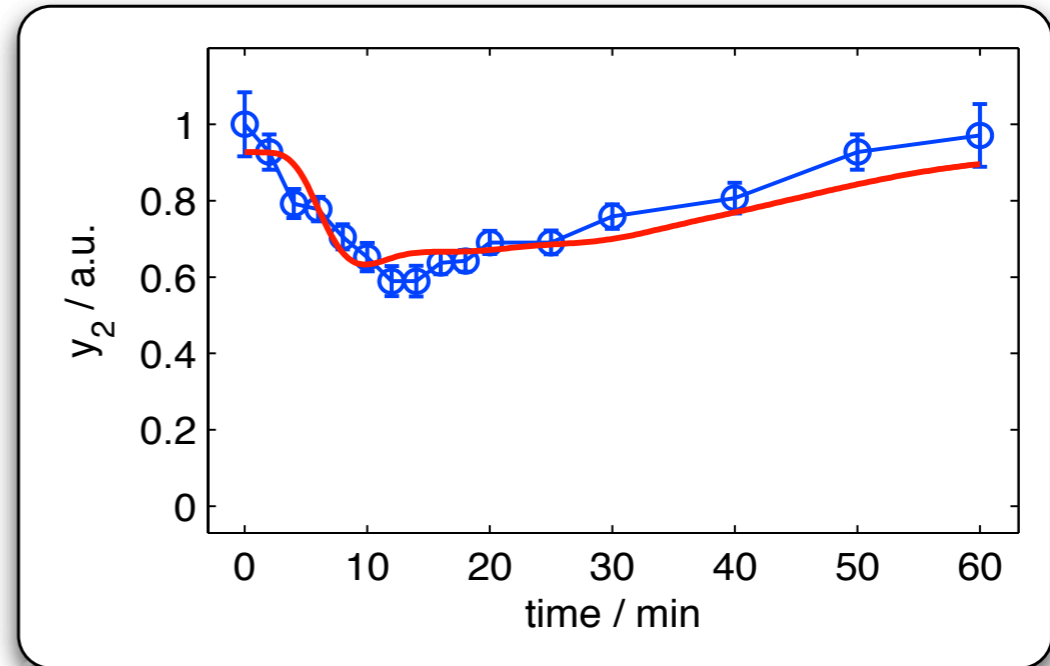
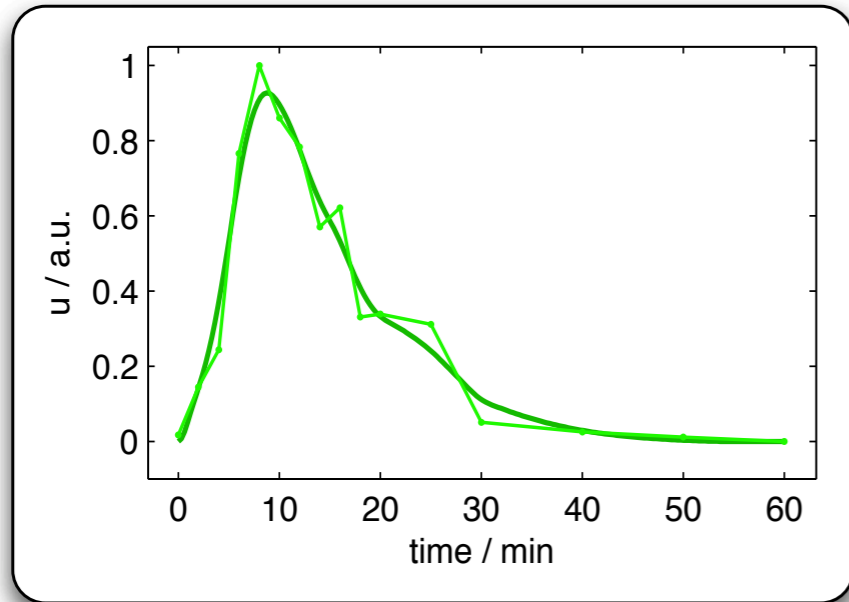
Raue A., Kreutz C., Maiwald T., Bachmann J., Schilling M., Klingmüller U., Timmer J.
Structural and practical identifiability analysis of partially observed dynamical models by exploiting the profile likelihood. Bioinformatics, in press

I. Profile Likelihood Approach

Computational complexity

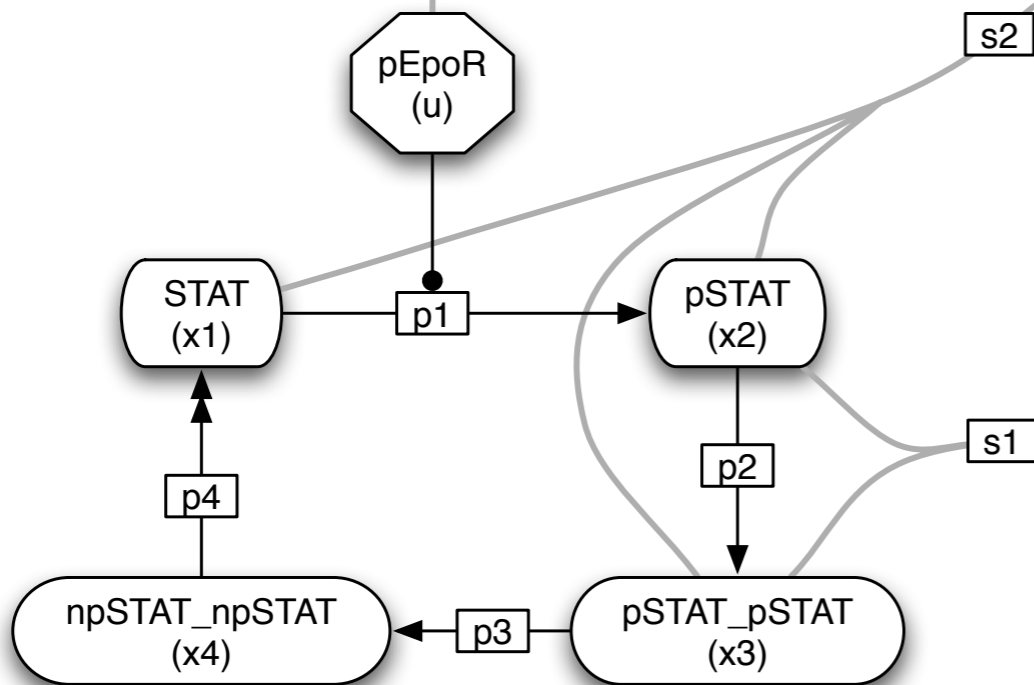
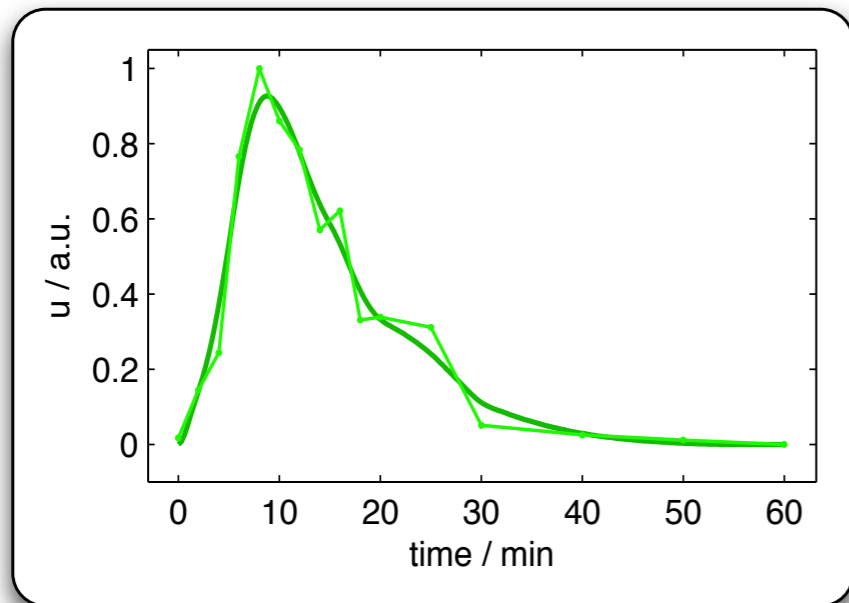


JAK-STAT Signaling Pathway



Swameye, I., Müller, T. G., Timmer, J., Sandra, O., and Klingmüller, U. (2003). *Identification of nucleocytoplasmic cycling as a remote sensor in cellular signaling by databased modeling*. PNAS, 100(3), 1028–1033.

JAK-STAT Signaling Pathway



ODE model

$$\begin{aligned}\dot{x}_1 &= -p_1 x_1 u + 2p_4 x_4^\tau \\ \dot{x}_2 &= +p_1 x_1 u - p_2 x_2^2 \\ \dot{x}_3 &= +0.5p_2 x_2^2 - p_3 x_3 \\ \dot{x}_4 &= +p_3 x_3 - p_4 x_4^\tau\end{aligned}$$

$$y_1 = s_1(x_2 + 2x_3)$$

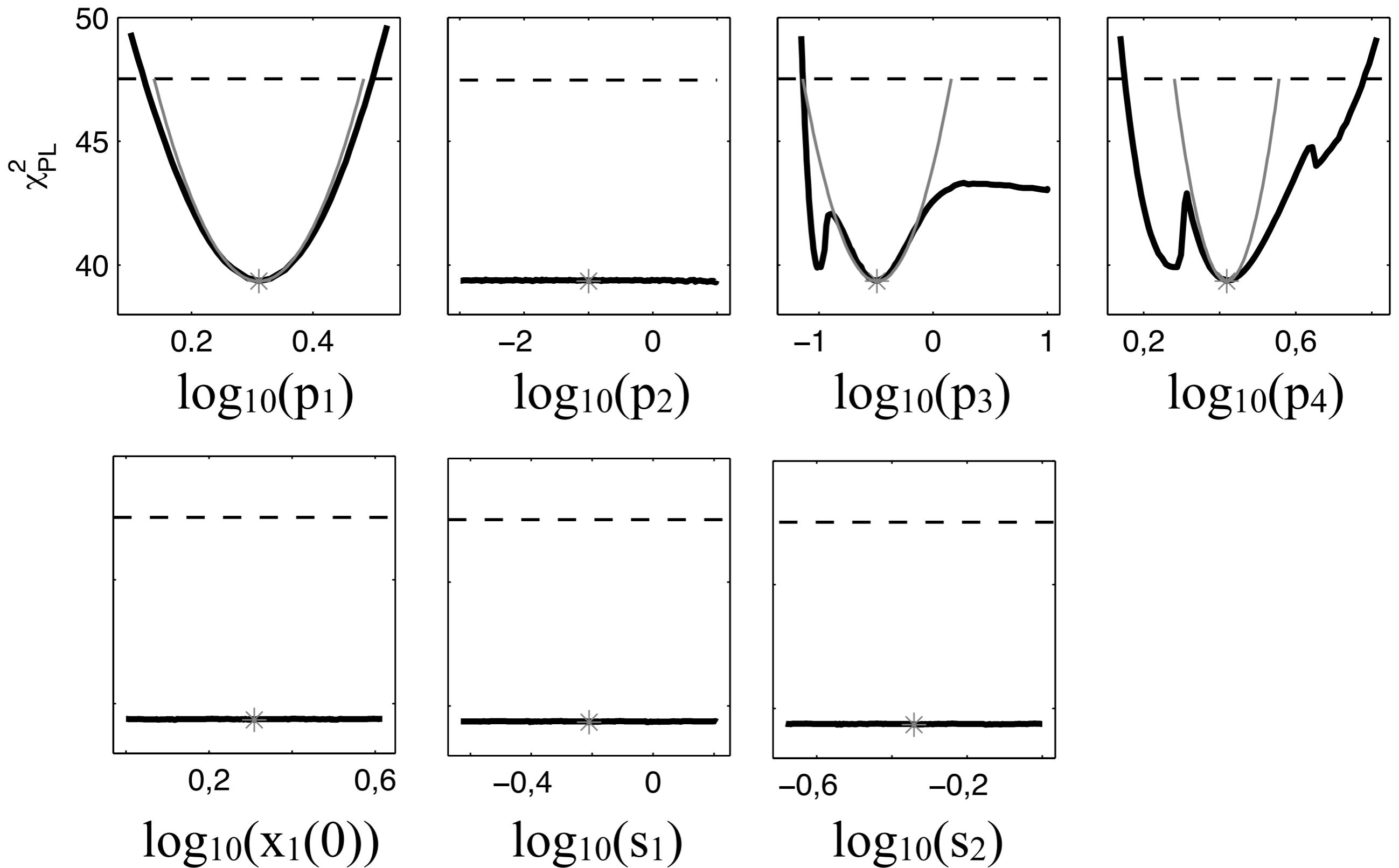
$$y_2 = s_2(x_1 + x_2 + 2x_3)$$

Structural non-identifiability

$$\{p_2, x_1(0), s_1, s_2\}$$

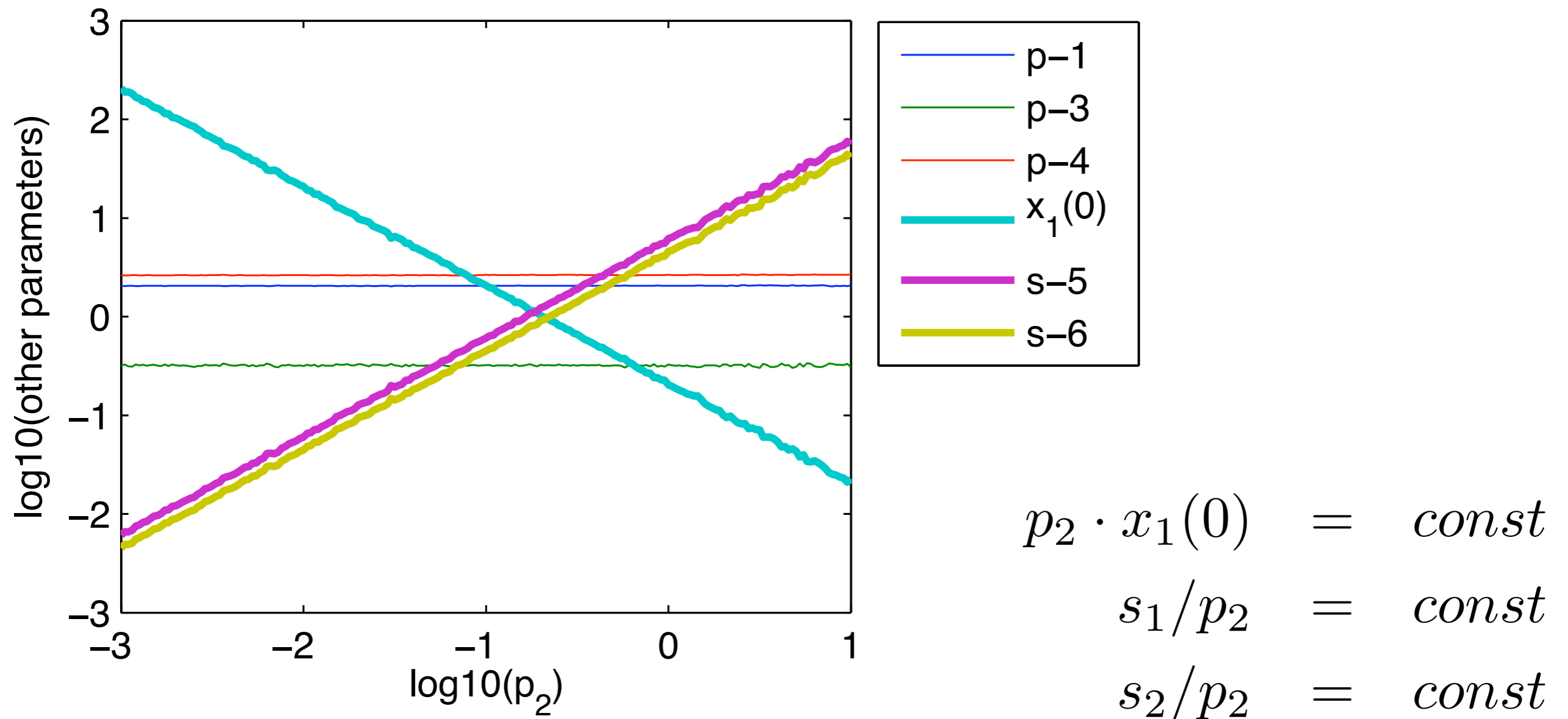
Swameye, I., Müller, T. G., Timmer, J., Sandra, O., and Klingmüller, U. (2003). *Identification of nucleocytoplasmic cycling as a remote sensor in cellular signaling by databased modeling*. PNAS, (3), 1028–1033.

JAK-STAT Signaling Pathway



JAK-STAT Signaling Pathway

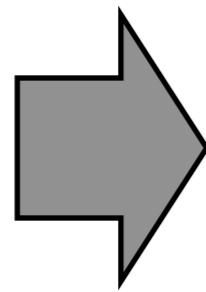
Functional relations between $\{p_2, x_1(0), s_1, s_2\}$



2. Mean *Optimal Transformation* Approach

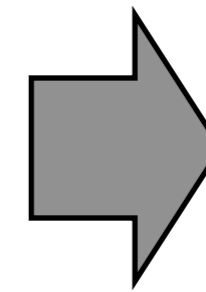
Profile Likelihood
Approach

Parameter 1
Parameter 2
Parameter 3
Parameter 4
Parameter 5
Parameter 6
Parameter 7
Parameter 8
Parameter 9
...



structurally non-identifiable
structurally non-identifiable
structurally non-identifiable
structurally non-identifiable
structurally non-identifiable
structurally non-identifiable
...

Mean Optimal
Transformation
Approach



Group 1
Group 2
Group 1
Group 1
Group 2
...

2. Mean *Optimal Transformation* Approach

Hengl S., Kreutz C., Timmer J., Maiwald T. *Data-based identifiability analysis of nonlinear dynamical models*. *Bioinformatics* 23, 2007, 2612-2618

Idea:

1. Multiple fitting

2. *Optimal Transformation*

$$\{\Theta, \Phi\} = \sup_{\hat{\Theta}, \hat{\Phi}} |R(\hat{\Theta}(p_i), \hat{\Phi}(p_j))|$$

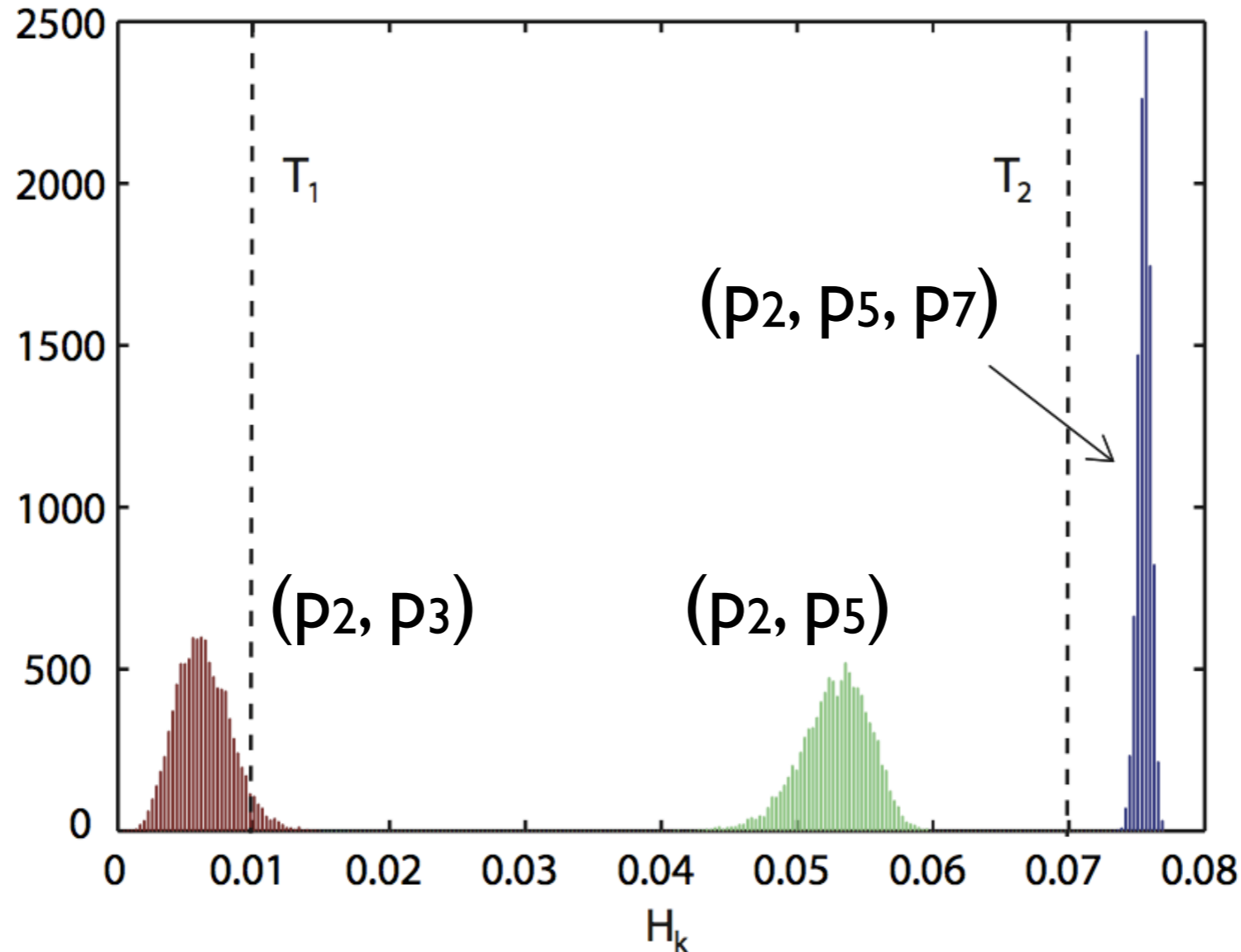
by *Alternating Conditional Expectation* algorithm.

3. Bootstrap

Breiman L., Friedman J. H. *Estimating optimal transformations for multiple regression and correlation*. *Journal American Statistical Association* 80, 1985, 580–598

2. Mean *Optimal Transformation* Approach

Test statistics H_k



Independency Optimal transformations change every time

Not yet decidable

Dependency Optimal transformation is reproduced

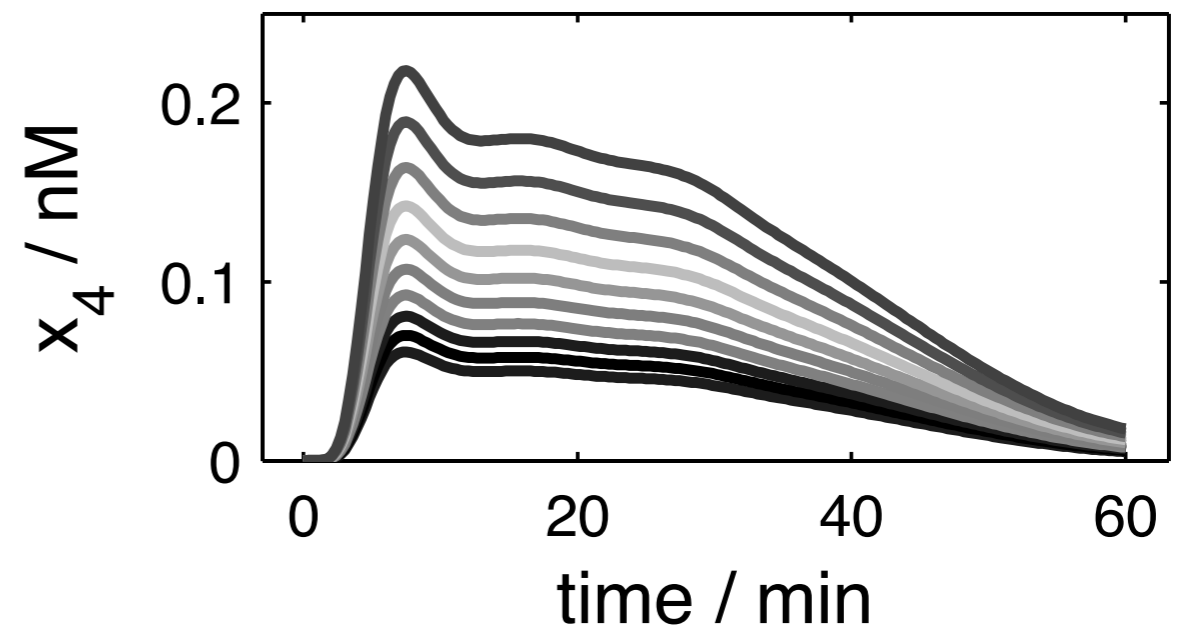
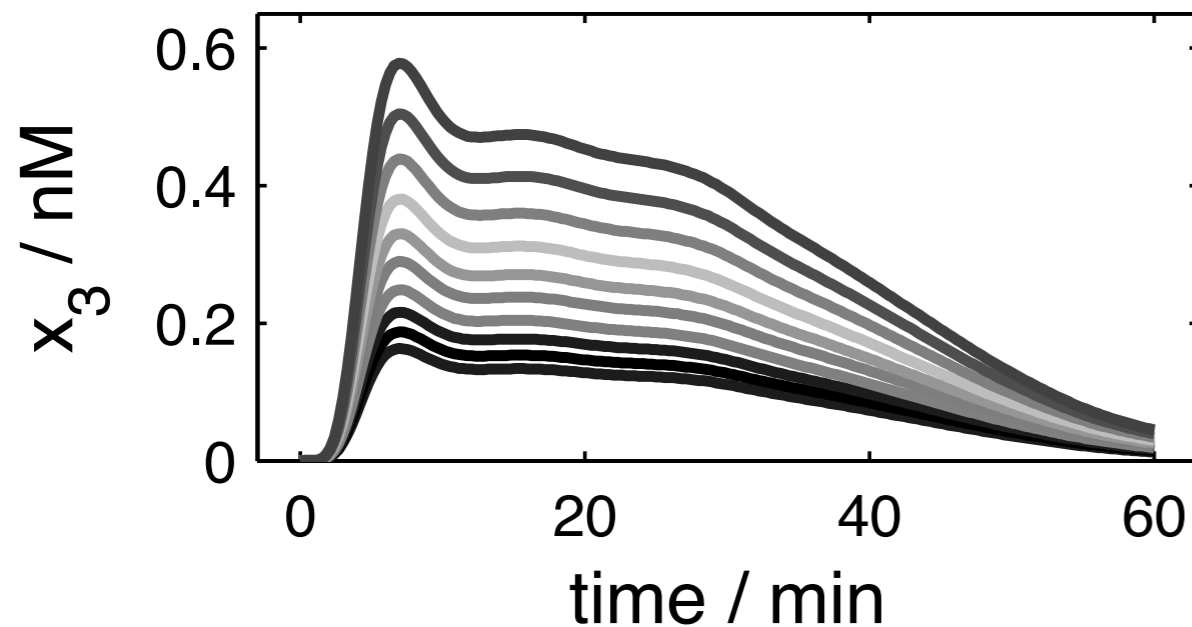
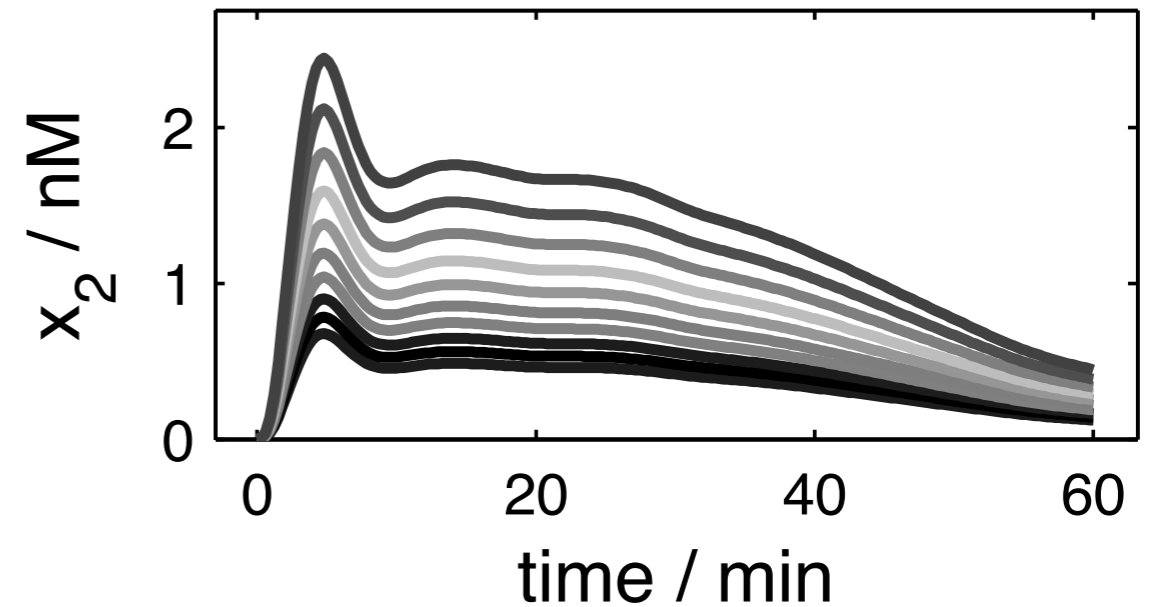
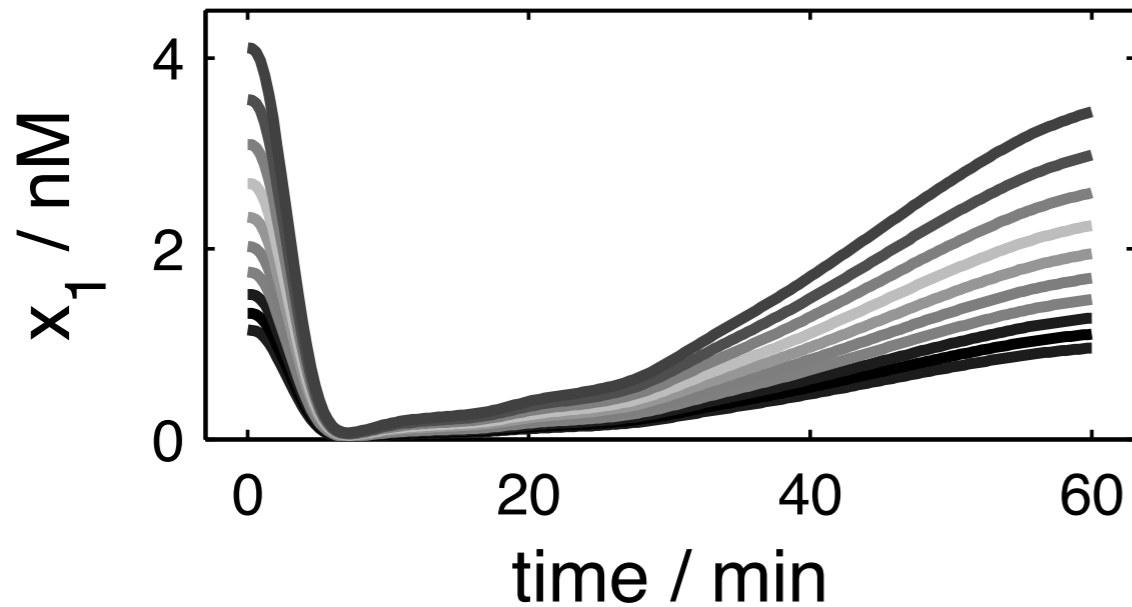
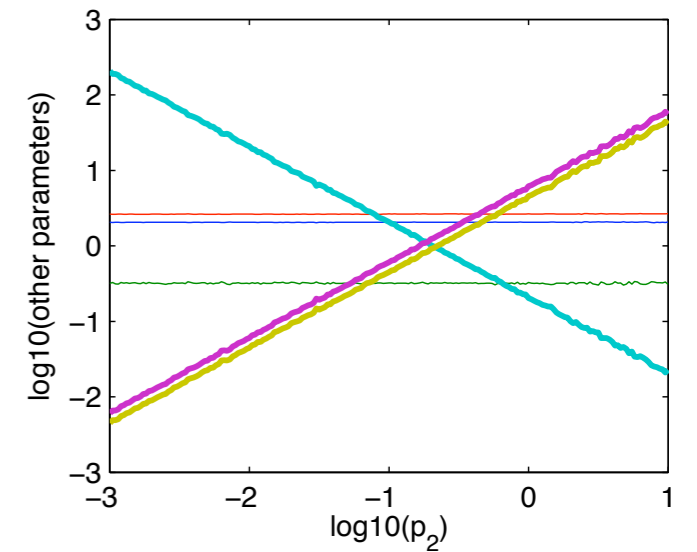
2. Mean *Optimal Transformation* Approach

Parameter 2	1	1	1	0	0
Parameter 5	1	1	1	0	0
Parameter 7	1	1	1	0	0
Parameter 3	0	0	0	1	1
Parameter 8	0	0	0	1	1

Experimental Design

Structural non-identifiability

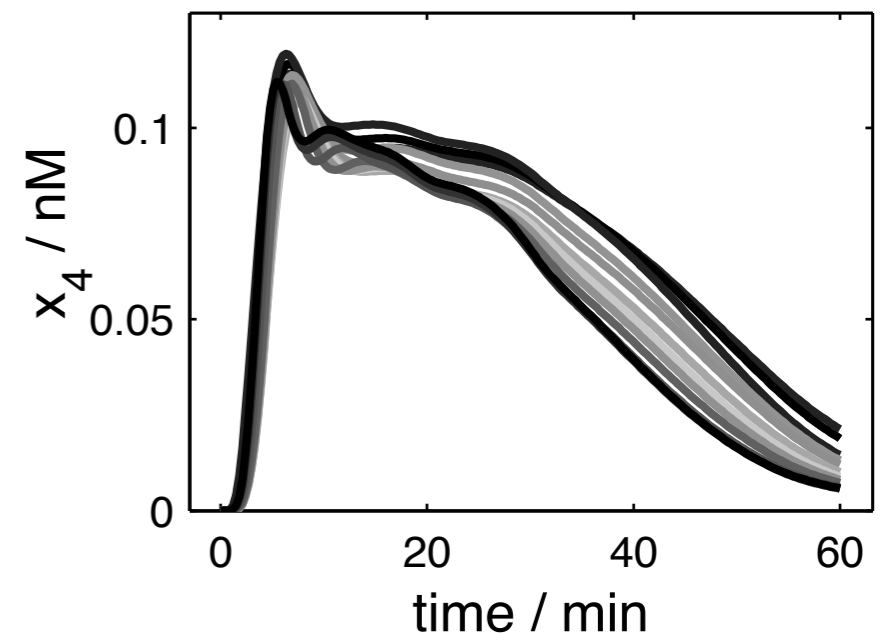
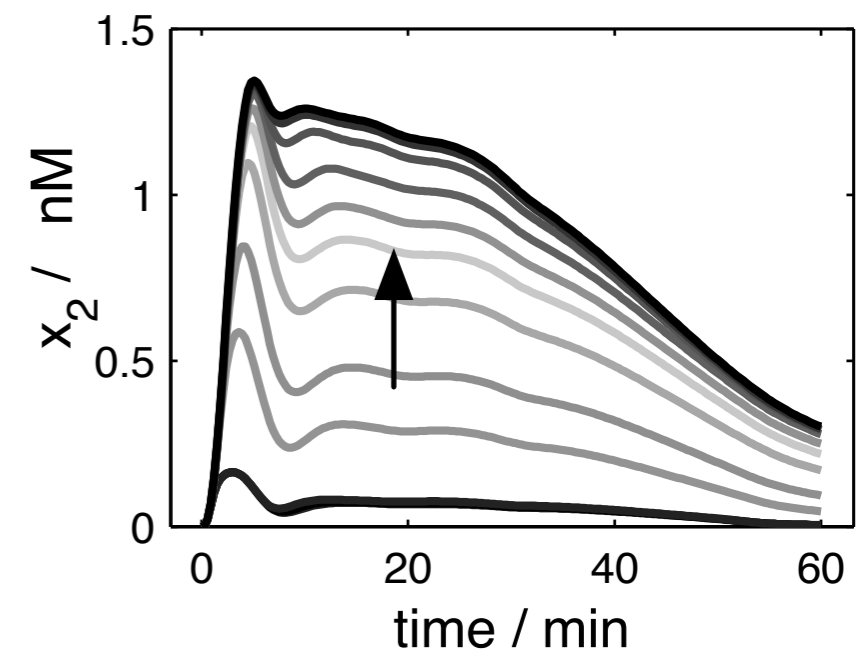
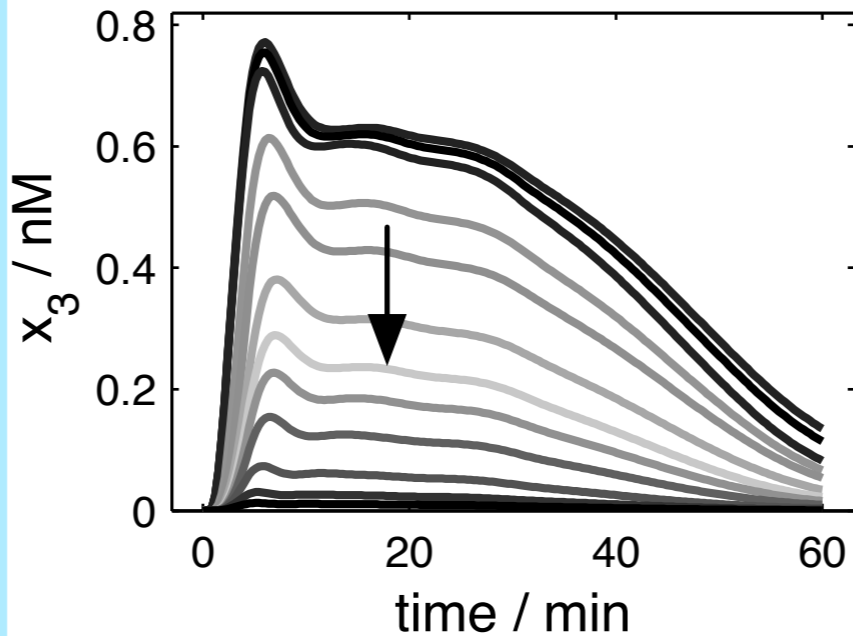
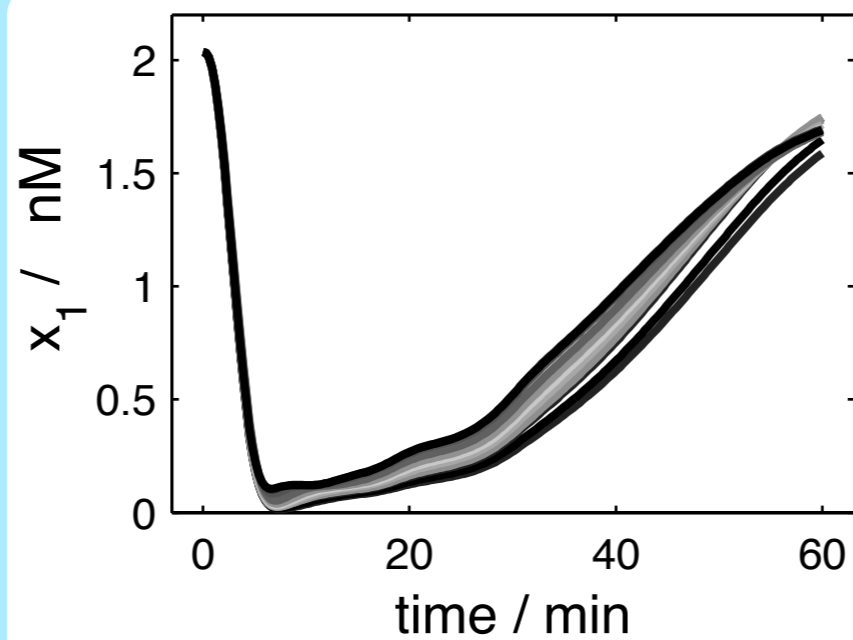
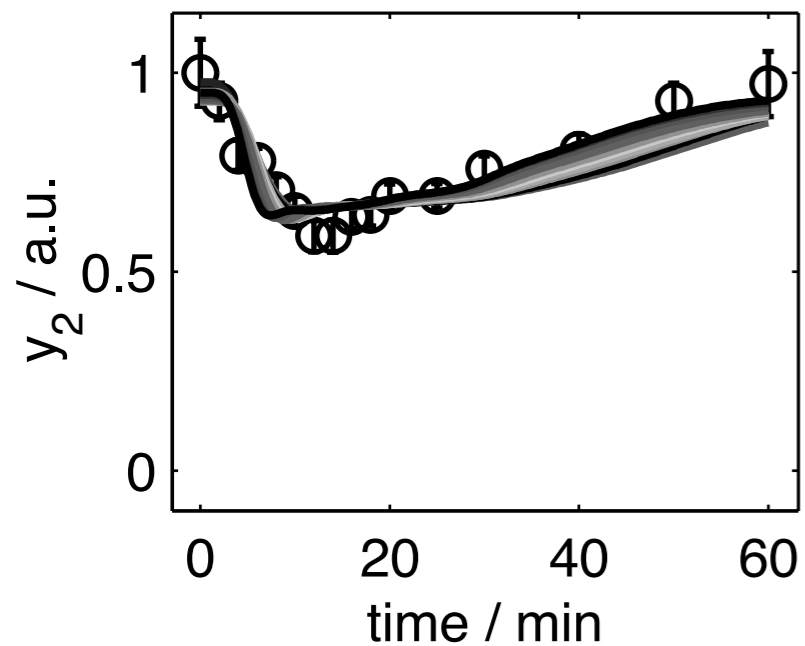
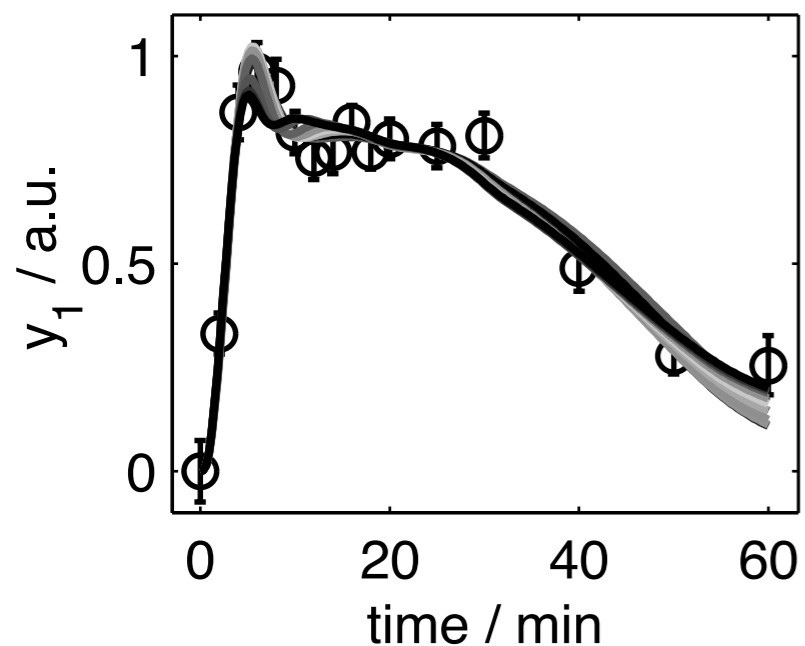
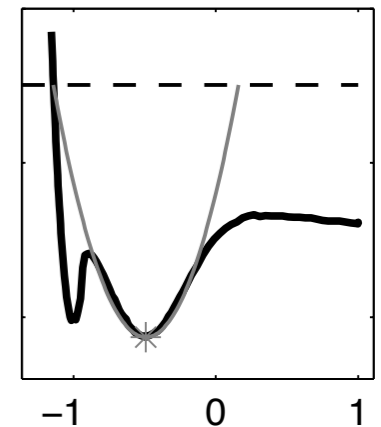
$$\{p_2, x_1(0), s_1, s_2\}$$



Experimental Design

Practical non-identifiability

$\log_{10}(p_3)$



Summary

- Two data-based approaches to detect and analyse structural and practical non-identifiabilities
- Facilitating experimental design to build predictive models

Acknowledgements



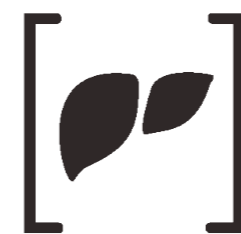
Jens Timmer

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Seong-Hwan Rho
Stefan Jansen
Daniel Kaschek



Ursula Klingmüller

Marcel Schilling
Julie Bachmann
Sebastian Bohl
Verena Becker



Network Systems Biology

HepatoSys